

Tutorial 1:

1. $\begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$, $\begin{bmatrix} 1 & * \\ 0 & 0 \end{bmatrix}$, $\begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}$, $\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$

"0" only one pivot only one pivot "I"

A: Row reduced $\rightarrow$ see in defn of row-reduced echelon matrix

2. $A = \begin{bmatrix} 3 & -1 & 2 \\ 2 & -1 & 1 \\ 1 & -3 & 0 \end{bmatrix}$ $y = \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix}$ $Ax = y$

let $A = \begin{bmatrix} 3 & -1 & 2 \\ 2 & -1 & 1 \\ 1 & -3 & 0 \end{bmatrix} \xrightarrow{R'_3 = R_3 - \frac{1}{3}R_1} \begin{bmatrix} 3 & -1 & 2 \\ 2 & -1 & 1 \\ 0 & -\frac{2}{3} & -\frac{2}{3} \end{bmatrix} \xrightarrow{R'_2 = R_2 - \frac{2}{3}R_1} \begin{bmatrix} 3 & -1 & 2 \\ 0 & \frac{5}{3} & -\frac{1}{3} \\ 0 & -\frac{2}{3} & -\frac{2}{3} \end{bmatrix}$

$\swarrow R'_3 = R_3 + \frac{8}{5}R_2$

$$\begin{bmatrix} 3 & -1 & 2 \\ 0 & \frac{5}{3} & -\frac{1}{3} \\ 0 & 0 & -\frac{6}{5} \end{bmatrix}$$

$y = \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix} \xrightarrow{R'_3 = R_3 - \frac{1}{3}R_1} \begin{bmatrix} y_1 \\ y_2 \\ y_3 - \frac{y_1}{3} \end{bmatrix} \xrightarrow{R'_2 = R_2 - \frac{2}{3}R_1} \begin{bmatrix} y_1 \\ y_2 - \frac{2}{3}y_1 \\ y_3 - \frac{y_1}{3} \end{bmatrix} \xrightarrow{R'_3 = R_3 + \frac{8}{5}R_2} \begin{bmatrix} y_1 \\ y_2 - \frac{2}{3}y_1 \\ y_3 - \frac{y_1}{3} + \frac{8}{5}(y_2 - \frac{2}{3}y_1) \end{bmatrix}$

now for $y_3 - \frac{y_1}{3} + \frac{8}{5}(y_2 - \frac{2}{3}y_1) \neq 0$ it has a unique soln.

$$y_3 - \frac{y_1}{3} + \frac{8}{5}y_2 - \frac{16}{15}y_1 \neq 0$$

$$y_3 + \frac{8}{5}y_2 - \frac{21}{15}y_1 \neq 0$$

$$y_3 + \frac{8}{5}y_2 - \frac{7}{5}y_1 \neq 0$$

$$5y_3 + 8y_2 - 7y_1 \neq 0$$

3. A (n x n) matrix

(P) $\exists B_{n \times n}$ s.t.
 $BA = I$

as $BA = I$

if $AB = I$ then

A is invertible.

as $BA = I$

$$BAB = B$$

$$ABAB = AB$$

$$(AB)^2 = AB$$

$$\begin{aligned} \text{as } AB &= (AB)^2 \\ AB &= (AB)^n \quad \forall n \in \mathbb{N} \\ (AB)^2 - AB &= 0 \end{aligned}$$

$$\begin{aligned} (AB)(AB - I) &= 0 \\ AB &= 0 \\ \text{or } AB &= I \end{aligned}$$

$$\begin{aligned} \text{but } AB &\neq 0 \quad \text{as if } AB = 0 \\ AB \cdot A &= 0 \\ A &= 0 \\ \text{but as } BA &= I \\ A &\neq 0 \quad * \end{aligned}$$

$$\begin{aligned} \therefore AB &= I = BA \\ \therefore A &\text{ is invertible} \end{aligned}$$

(ii) $AC = I$ similar to (i).

$$9. \quad A = \begin{bmatrix} 1 & -1 \\ 2 & 2 \\ 1 & 0 \end{bmatrix}_{3 \times 2} \quad B = \begin{bmatrix} 3 & 1 \\ -4 & 4 \end{bmatrix}_{2 \times 2} \quad \text{To find } C \text{ and if unique.}$$

C has to be 2×3

$$\text{let } C = \begin{bmatrix} c_{11} & c_{12} & c_{13} \\ c_{21} & c_{22} & c_{23} \end{bmatrix}$$

$$\begin{bmatrix} c_{11} & c_{12} & c_{13} \\ c_{21} & c_{22} & c_{23} \end{bmatrix} \begin{bmatrix} 1 & -1 \\ 2 & 2 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} 3 & 1 \\ -4 & 4 \end{bmatrix}$$

$$c_{11} + 2c_{12} + c_{13} = 3$$

$$-c_{11} + 2c_{12} = 1$$

$$2c_{12} - 1 = c_{11}$$

$$2c_{12} - 1 + 2c_{12} + c_{13} = 3$$

$$4c_{12} + c_{13} = 4$$

$$c_{13} = 4 - 4c_{12}$$

$$c_{11} = 2c_{12} - 1$$

$$c_{12} = c_{12}$$

$$\begin{aligned} c_{21} + 2c_{22} + c_{23} &= -4 \\ -c_{21} + 2c_{22} &= 4 \end{aligned}$$

$$2c_{22} - 4 = c_{21}$$

$$2c_{22} - 4 + 2c_{22} + c_{23} = -4$$

$$4c_{22} + c_{23} = 0$$

$$c_{23} = -4c_{22}$$

$$c_{22} = c_{22}$$

$$c_{21} = 2c_{22} - 4$$

$$\begin{bmatrix} 2c_{12} - 1 & c_{12} & 4 - 4c_{12} \\ 0 & 0 & 0 \end{bmatrix} + \begin{bmatrix} 0 & 0 & 0 \\ 2c_{22} - 4 & c_{22} & -4c_{22} \end{bmatrix}$$

$$= \begin{bmatrix} -1 & 0 & 4 \\ -4 & 0 & 0 \end{bmatrix} + c_{12} \begin{bmatrix} 2 & 1 & -4 \\ 0 & 0 & 0 \end{bmatrix} + c_{22} \begin{bmatrix} 0 & 0 & 0 \\ 2 & 1 & -4 \end{bmatrix}$$

5. $A_{m \times n}$
 $B_{n \times m}$ $n < m$
 AB is non-invertible.
 AB is $m \times m$
 AB $m \times m$ is non-invertible

as $A \times B = A_{1*} \cdot B_{*1} + A_{2*} \cdot B_{*2} + \dots$

as A, B can have max n pivots

$$A \cdot B = \begin{bmatrix} A_{1*} \\ \vdots \\ A_{m*} \end{bmatrix} \cdot \begin{bmatrix} B_{*1} & B_{*2} & \dots \end{bmatrix}$$

row reduced form of A with n pivots is:

$$\begin{bmatrix} 1 & & 0 \\ & \ddots & \\ 0 & & 1 \end{bmatrix} \text{ for } B: \begin{bmatrix} 1 & & 0 \\ & \ddots & \\ 0 & & 1 \end{bmatrix}$$

$$r(A) \cdot r(B) = \begin{bmatrix} 1 & & 0 \\ & \ddots & \\ 0 & & 1 \end{bmatrix}_{n \times n} \text{ so row reduced form of } A \cdot B \text{ can have max } n \text{ pivots.}$$

as $n < m$, AB is invertible

6. $B \in M_{n \times n}(\mathbb{C})$

(i) To prove: $B' = \{A \in M_{n \times n}(\mathbb{C}) \mid AB = BA\}$
 is a subspace.

proof: for $A, C \in B'$ $AB = BA$ and $CB = BC$
 $\alpha \in \mathbb{C}$

if $\alpha A + C \in B'$ (proved)

$$\begin{aligned} \text{now } (\alpha A + C)B &= \alpha AB + CB \\ &= \alpha BA + BC \\ &= B\alpha A + BC \\ &= BC\alpha A + C \\ &= B(\alpha A + C) \end{aligned}$$

$\therefore \alpha A + C \in B'$
 $\therefore$ subspace

(ii) $B = \begin{bmatrix} 1 & & 0 \\ & \ddots & \\ 0 & & n \end{bmatrix}_{n \times n}$ to find: $B' = \{A \in M_{n \times n}(\mathbb{C}) \mid AB = BA\}$
 for $B = \begin{bmatrix} 1 & & 0 \\ & \ddots & \\ 0 & & n \end{bmatrix}_{n \times n}$

$$\text{let } A = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & \cdot & \cdot & a_{2n} \\ \vdots & \cdot & \cdot & \vdots \\ a_{n1} & \cdot & \dots & a_{nn} \end{bmatrix}_{n \times n} \quad \forall a_{ij} \in \mathbb{C}, A \in M_{n \times n}(\mathbb{C})$$

$$\text{now } AB = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & a_{nn} \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 3 \cdot n \end{bmatrix} = \begin{bmatrix} a_{11} & 2a_{12} & 3a_{13} & \dots & na_{1n} \\ a_{21} & 2a_{22} & \cdot & \cdot & na_{2n} \\ \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & na_{nn} \end{bmatrix}$$

$$BA = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 3 \cdot n \end{bmatrix} \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & a_{nn} \end{bmatrix} = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ 2a_{21} & 2a_{22} & \dots & 2a_{2n} \\ na_{31} & na_{32} & \dots & na_{3n} \end{bmatrix}$$

$$\text{for } AB = BA$$

a_{11}, a_{nn} can be anything in $\mathbb{C}$

$$\text{as } 2a_{21} = a_{21}$$

$$\Rightarrow a_{21} = 0 \quad (\text{similarly for others})$$

similarly a_{ii} can be any value.

$$\text{so } B' = \begin{bmatrix} a_1 & & 0 \\ & a_2 & \\ 0 & & \ddots \\ & & & a_n \end{bmatrix}$$

where diagonal element can be anything in $\mathbb{C}$

$$\text{so } \forall a_i \in \mathbb{C}, B'$$

$$7. x = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} \in M_{n \times 1}(\mathbb{C})$$

$$LA(x) = \{A \in M_{n \times n}(\mathbb{C}) \mid Ax = 0\}$$

(i) for $LA(x)$ to be a subspace of $M_{n \times n}(\mathbb{C})$:
let $\alpha \in \mathbb{C}$

$$A_1, A_2 \in LA(x)$$

$$\begin{aligned} \text{then } A_1 x &= 0 \text{ and } A_2 x = 0 \\ \Rightarrow \alpha A_1 x &= 0 \text{ and } A_2 x = 0 \\ \Rightarrow (\alpha A_1 + A_2) x &= 0 \\ \Rightarrow \alpha A_1 + A_2 &\in LA(x) \\ \therefore \text{proved.} \end{aligned}$$

(ii) To prove: $BA \in LA(x)$ whenever (left ideal)
 $A \in LA(x)$ and $B \in M_{n \times n}(\mathbb{C})$

$$\text{proof: as } A \in LA(x) \\ Ax = 0$$

$$\text{now if } B \in M_{n \times n}(\mathbb{C})$$

$$\begin{aligned} \text{then } B(Ax) &= B \cdot 0 = 0 \\ \Rightarrow (BA)x &= 0 \Rightarrow BA \in LA(x) \end{aligned}$$

(iii) To prove: $LA(X) = M_{n \times n}(\mathbb{C}) \Leftrightarrow X = 0$

proof: ($\Rightarrow$) given $LA(X) = M_{n \times n}(\mathbb{C})$

then
 $I \in LA(X)$
so $IX = 0$
 $\Rightarrow X = 0$

($\Leftarrow$) $X = 0$, $\forall A \in M_{n \times n}(\mathbb{C})$

$A \cdot 0 = 0$
i.e. $AX = 0$
so $M_{n \times n}(\mathbb{C}) = LA(X)$

8. $A, B \in M_{n \times n}(\mathbb{C})$ s.t. $AB = 0$

(i) $BA = 0$

false: counter-example:

$$A = \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix} \quad B = \begin{bmatrix} 1 & 0 \\ 1 & 0 \end{bmatrix} \quad AB = 0$$

$$BA = \begin{bmatrix} 1 & 0 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} = BA \neq 0$$

(ii) false (above)

(iii) Proof:

as B is invertible, $\exists C$ s.t. $BC = I = CB$
 $C = B^{-1}$

now,

for $AB = 0$

$$ABC = 0 \cdot C = 0$$

$$\Rightarrow A(BC) = 0$$

$$\Rightarrow A \cdot I = 0$$

$$\Rightarrow A = 0$$

(iv) for $x \neq 0$ but $BAx = 0$

BA have to be non-invertible

$$\text{as } |AB| = |BA| = 0$$

BA is non-invertible
 $\therefore$ possible.

$$(A, B \in M_{n \times n}(\mathbb{C}))$$

as $AB = 0$

$$ABx = 0$$

so for $x = B^{-1}1$

so for $B^{-1}1 \neq 0$

for $n \neq 0$

works.

for

$$B^{-1}1 = 0$$

if all $B^{-1}i \neq 0$

$$B^{-1}i = 0$$

$$AB = 0$$

$$\text{then } ABx = 0$$

$$\forall x \in \mathbb{R}^n$$

possible

$$\therefore x \neq 0$$

$$ABx = 0$$

Tutorial - 2 :

$$1. \begin{bmatrix} 1 & 2 & 1 & 2 \\ 1 & -1 & -1 & 1 \\ 2 & -5 & -4 & 1 \\ 4 & 2 & 0 & 6 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 2 & 1 & 2 \\ 0 & -3 & -2 & -1 \\ 0 & -9 & -6 & -3 \\ 0 & -6 & -4 & -2 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 2 & 1 & 2 \\ 0 & -3 & -2 & -1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

lin dep in $\mathbb{R}^4$

$$2. \forall V \in M_{2 \times 2}(\mathbb{Q}) = V$$

$$(i) \left\{ \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \right\}$$

can form

$$v = \begin{bmatrix} v_1 & v_2 \\ v_3 & v_4 \end{bmatrix} \in V$$

Note: ① spans $V \Rightarrow$ Basis
② lin ind
③ (Basis) = dim

$$\therefore \dim = 4$$

$$(ii) W = \{A \in M_{2 \times 2}(\mathbb{Q}) \mid A_{11} + A_{22} = 0\}$$

$$W = \left\{ \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} \mid a_{11} + a_{22} = 0 \right\}$$

$$= \left\{ \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & -a_{11} \end{bmatrix} \in M_{2 \times 2}(\mathbb{Q}) \right\}$$

$$\left\{ \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \right\} \text{ can form } W.$$

$$\therefore \dim W = 3$$

also if $\alpha w_1 + \beta w_2 \in W$
then W is a subspace.

$$\text{here } \alpha w_1 + \beta w_2$$

$$\begin{aligned} \alpha a_{11} + \beta b_{11} &= w_{11} \\ -\alpha a_{11} - \beta b_{11} &= w_{22} \end{aligned}$$

$$\text{as } w_{11} + w_{22} = 0$$

$$\alpha w_1 + \beta w_2 \in W$$

$$3. X = \text{span}\{1, x, x^2, \dots, x^n\}$$

$$Y = \{f(x) \in X \mid f(x) = 0 \text{ at } x = t_1, t_2, \dots, t_j \text{ for } j < n\}$$

$$(i) f(t_i) = 0 \text{ also let}$$

$$f(x) \in Y$$

$$\text{and } g(x) \in Y$$

$$\text{then } \alpha f(x) + \beta g(x) \in Y$$

$$\text{as for } x = t_1, t_2, \dots, t_j$$

$$\text{both are zero}$$

$$\Rightarrow \alpha(0) + \beta(0) = 0$$

$X =$ set of poly deg $< n$

$$Y = \{f(x) \mid f(t_i) = 0, i \in \{1, 2, \dots, j\}\}$$

$$f(x) \in Y$$

$$(ii) f(x) = a(x-t_1)(\dots)$$

↓
remains same

$$a \in \mathbb{R} \text{ s.t. } a \neq 0$$

$$\therefore \deg Y = 2$$

$$\text{as } \text{span } Y = \{a, (x-t_1)(x-t_2)\dots(x-t_j)\}$$

$$(iii) \dim(X/Y) = \{x \mid x \in X\}$$

↳ polynomials

with zero = $t_1, t_2, \dots, t_j$

$$\text{span}(X/Y) = \{a, x, x^2, \dots, x^{n-j}, (x-t_1)(x-t_2)\dots(x-t_j)\}$$

$$\deg(X/Y) = n-j+1+1 = n-j+2$$

By span Y:

$$\Rightarrow \phi(x) = \prod_{i=1}^j (x-t_i) Q(x)$$

$$\text{where, } Q(x) = \sum_{k=0}^{n-j-1} b_k x^k$$

$$\phi(x) = \prod_{i=1}^j (x-t_i) \left(\sum_{k=0}^{n-j-1} b_k x^k \right)$$

$$= \sum_{k=0}^{n-j-1} \left\{ \prod_{i=1}^j (x-t_i) \right\} x^k$$

4. V = vector space
 A = lin ind subset of V

A = basis of $V \iff A$ is a maximal lin ind subset of V

① $\text{span } A = V$ ② any addition of vector $\rightarrow$ lin dep

proof:

$$(\Rightarrow) A = \text{basis of } V$$

$$\text{span } A = V$$

$$A \text{ is lin ind}$$

let $\dim A = n$ so

$$A = \{v_1, v_2, \dots, v_n\}$$

s.t if $\sum a_i v_i = 0$
 $\Rightarrow a_1 = a_2 = \dots = a_n = 0$

now if we add v_{n+1} to A

$$v_{n+1} \in V$$

then as $\text{span } A = V$

$$v_{n+1} = \sum b_i v_i$$

then as v_{n+1} can be written as form $\sum b_i v_i$ as $\text{span } A = V$

$$\{v_1, v_2, \dots, v_n, v_{n+1}\} \text{ is lin dependent}$$

$$\sum_{i=1}^n b_i v_i$$

$$\text{so for } a_i = -b_i$$

$\therefore A$ is maximal lin ind subset of V .

$$\text{then } \phi(x) = (x-t_1)\dots(x-t_j) Q(x)$$

$$\deg(Q(x)) < n-j$$

$$B_Y = \left\{ \prod_{i=1}^j (x-t_i), \prod_{i=1}^j (x-t_i)x, \dots, \prod_{i=1}^j (x-t_i)x^{n-j-1} \right\}$$

Claim: B_Y forms basis of Y

① so, by span Y

② B_Y is lin ind:

$$\sum_{k=0}^{n-j-1} b_k \left(\prod_{i=1}^j (x-t_i) \right) x^k = 0, \forall x$$

But $\deg \left(\sum_{k=0}^{n-j-1} \left(\prod_{i=1}^j (x-t_i) \right) x^k \right) < n-j$

poly of degree $< n-j$

so almost $n-j$ zeros, only if all are zero $\Rightarrow b_k = 0$

Note: Better

case:

$$\{1, (t-t_1), (t-t_1)(t-t_2), \dots, (t-t_1)\dots(t-t_j)\}$$

$$\prod_{i=1}^j (t-t_i)$$

($\Leftarrow$) if A is max lin ind subset of V .

then

if v_{n+1} is added

to A

A is lin dependent

$$\text{so } v_{n+1} = \sum_{i=1}^n a_i v_i$$

$$\forall v_i \in A$$

but as $v_{n+1} \in V$

$$\text{span } A = \sum_{i=1}^n a_i v_i = V$$

$\therefore A$ is basis of V

5. $\text{span}(A) = V$

$$A \subseteq V$$

A is a basis of $V \Leftrightarrow A$ is a minimal spanning set

$$\textcircled{1} \text{span } A = V$$

$$\textcircled{2} A \text{ is lin ind}$$

$\textcircled{1}$ if we remove a vector
 $\text{span } A \neq V$

proof:

($\Rightarrow$) $\text{span } A = V$ and A is lin ind (as A is basis)

let

$$A = \{v_1, v_2, \dots, v_n\}, \text{ if we remove } v_n \text{ (WLOG)}$$

but as $v_n \in V$

$$\sum a_i v_i \neq v_n$$

$$\therefore \text{span } A \neq V$$

$\therefore A$ is a minimal spanning set of V .

($\Leftarrow$) $\text{span } A = V$ and A is minimal spanning set
then if we prove A is lin ind then we are done.

$$A = \{v_1, v_2, \dots, v_n\} \text{ s.t. } \text{span } A = V$$

if we remove v_n (WLOG)

$$\text{span}\{v_1, v_2, \dots, v_{n-1}\} \neq V$$

if A was lin dependent
then $\sum_{i=1}^n a_i v_i = v_n$

$$\therefore \text{span}\{v_1, v_2, \dots, v_{n+1}\} = V \quad *$$

$\therefore A$ is lin ind.

$\therefore A$ is basis of V .

Tutorial-3:

$$1. C([0,1]) = \{f: [0,1] \rightarrow \mathbb{C} \mid f \text{ is cont}\}$$

$$T: C([0,1]) \rightarrow \mathbb{C}$$

$$T(f) = \int_0^1 f(x)x^3 dx, \forall f \in C([0,1])$$

for $T(f)$ to be a linear map:

$$T(f+g) = T(f) + T(g)$$

$$\text{and } T(\lambda f) = \lambda T(f)$$

$$\begin{aligned} \text{(i)} \quad T(f+g) &= \int_0^1 [f+g](x)x^3 dx \\ &= \int_0^1 f(x)x^3 dx + \int_0^1 g(x)x^3 dx \\ &= T(f) + T(g) \end{aligned}$$

$$\begin{aligned} \text{(ii)} \quad T(\lambda f) &= \int_0^1 \lambda f(x)x^3 dx = \lambda \int_0^1 f(x)x^3 dx \\ &= \lambda T(f) \end{aligned}$$

$\therefore T(f)$ is a linear map.

$$\text{define } C([0,1]) \rightarrow \mathbb{C} \text{ by } T(f) = \int_0^1 f(x)x^3 dx \quad \forall f \in C([0,1])$$

$$\text{claim: } T(\alpha f + g) = \alpha T(f) + T(g)$$

$$\forall f, g \in C([0,1])$$

$$\text{and } \alpha \in \mathbb{C}$$

$$T(\alpha f + g) = \int_0^1 (\alpha f + g)(x)x^3 dx$$

$$= \alpha \int_0^1 f(x)x^3 dx + \int_0^1 g(x)x^3 dx$$

$\therefore T$ is a linear map

Note: what we are trying to say is $T: V \rightarrow W$
 $T(V)$ becomes vector subspace of W .

$$2. X \leftarrow \text{vector space over } \mathbb{F} \\ x \in X \text{ and } x \neq \bar{0}$$

$$T(x) = \sum x_i$$

then

$$T(x+y) = \sum (x_i + y_i)$$

$$= \sum x_i + \sum y_i \\ = T(x) + T(y)$$

$$\begin{aligned} \text{and } T(\lambda x) &= \sum (\lambda x_i) \\ &= \lambda \sum x_i \\ &= \lambda T(x) \end{aligned}$$

$\therefore T(x) \neq 0$ is a linear map.

let X be a vector space over $\mathbb{F}$. Since x_0 is a non-zero vector, $\{x\}$ is a l.i. set in X .

Extend $\{x\}$ to basis B of X .

say $B = \{e_i\}_{i \in I} \cup \{x_0\}$. Define map

$$T: X \rightarrow \mathbb{F} \text{ by}$$

$$T\left(\sum_{i \in I} c_i e_i + d \cdot x_0\right) = d$$

(i) well defined

$$x=y \Rightarrow T(x)=T(y)$$

since

$$\begin{aligned} x=y &\Rightarrow T\left(\sum c_i e_i + d_1 x_0\right) \\ &= d_1 \\ T\left(\sum c_i e_i + d_2 x_0\right) &= d_2 \\ &= d_1 \end{aligned}$$

$$d_1 = d_2$$

$$\therefore T(x) = T(y)$$

(ii) $T(\alpha x + y)$

$$= T\left(\sum \alpha c_i e_i + (\alpha d_1 + d_2) x_0 + \sum \tilde{c}_i e_i\right)$$

$$= \alpha d_1 + d_2 \\ = \alpha T(x) + T(y)$$

$$3. C([-1,1]) = \{f: [-1,1] \rightarrow \mathbb{R} \mid f \text{ is cont}\}$$

$$P: C([-1,1]) \rightarrow C([-1,1])$$

$$(Pf)(x) = \frac{f(x) + f(-x)}{2}, \quad \forall x \in [-1,1] \text{ \& } f \in C([-1,1])$$

$$\text{now, } (P(f+g))(x) = \frac{(f+g)(x) + (f+g)(-x)}{2}$$

$$= \frac{f(x) + f(-x)}{2} + \frac{g(x) + g(-x)}{2}$$

$$= (Pf)(x) + (Pg)(x)$$

$$\text{and } (P(\lambda f))(x) = \frac{\lambda f(x) + \lambda f(-x)}{2}$$

Define $P: ([-1,1]) \rightarrow C([-1,1])$ by $(Pf)(x) = \frac{f(x) + f(-x)}{2}$

$$= \lambda \left(\frac{f(x) + f(-x)}{2} \right)$$

$$= \lambda(Pf)(x)$$

now $(Pf)(x) = \frac{f(x) + f(-x)}{2}$

we need to show that $P^2 = P$

$$\Leftrightarrow P^2(f) = P(Pf) = P\left(\frac{f(x) + f(-x)}{2}\right) = \frac{1}{2} \left(\frac{f(x) + f(-x)}{2} \right)$$

$$P(P(f)) = P(f)$$

$$P(Pf)(x) = \frac{(Pf)(x) + (Pf)(-x)}{2}$$

$$= \frac{Pf(x)}{2}$$

$$P(Pf) = Pf$$

$$+ \frac{1}{2} \left(\frac{f(-x) + f(x)}{2} \right)$$

$$= \frac{f(x) + f(-x)}{2}$$

$$= (Pf)(x)$$

$$\therefore P^2 = P$$

4. $X \leftarrow$ vector space of polynomials

$$T: X \rightarrow \mathbb{C}^n$$

$$T(P) = (P(s_1), \dots, P(s_n)), \forall P \in X$$

(i) $T(P_1 + P_2) = ((P_1 + P_2)(s_1), \dots, (P_1 + P_2)(s_n))$

$$= T(P_1) + T(P_2)$$

$$T(\lambda P) = (\lambda P(s_1), \dots, \lambda P(s_n)) = \lambda T(P)$$

(ii) $T: X \rightarrow \mathbb{C}^n$ by $T(P) = (P(s_1), \dots, P(s_n)), \forall P \in X$

$$\text{Basis } X = \{1, x, \dots, x^{n-1}\}$$

$$\deg X = n$$

$$P = \sum_{i=0}^{n-1} \alpha_i x^i = \alpha_0 + \alpha_1 x + \dots + \alpha_{n-1} x^{n-1}$$

now, $\mathbb{C}^n$ has deg of n .

$$\text{as } \deg X = \deg \mathbb{C}^n$$

$\Rightarrow X$ is isomorphic to $\mathbb{C}^n$

$\therefore T$ is one-one, onto and well defined

$$\therefore N_T = \{0\} \therefore N_T \text{ is trivial}$$

and T is onto, i.e. surjective.

Correction: $T: X \rightarrow \mathbb{C}^{n+1}$
 $s_0, s_1, s_2, \dots, s_n$ be distinct

$$T(P) = (P(s_0), P(s_1), \dots, P(s_n))$$

(ii) $N_T = \{P \in X \mid T(P) = (0, \dots, 0)\}$
 $P(s_0) = 0, \dots, P(s_n) = 0$

P of degree $n+1$ then by fundamental theorem of algebra it has $n+1$ roots

$$\therefore N_T = \{0\}$$

$$\therefore \dim N_T = 0$$

N_T is trivial

By rank-nullity theorem

$$\dim N_T + \dim R_T = \dim X$$

$$\dim R_T + 0 = n$$

$$\dim R_T = n$$

but $\dim \mathbb{C}^{n+1} = n+1$
 $\therefore$ Not surjective

Example: $v \in \mathbb{C}^{n+1}$

$$\text{s.t. } T(P) \neq v$$

$$P(s_n) = 1$$

(iii) $\int_0^1 p(x) dx = m_1 p(t_1) + \dots + m_n p(t_n), \forall p \in X$
 $t_i \in [0,1]$

proof: $\int_0^1 \sum_{i=0}^{n-1} \alpha_i x^i dx = \alpha_0 + \alpha_1 \int_0^1 x dx + \alpha_2 \int_0^1 x^2 dx$
 $+ \dots + \alpha_{n-1} \int_0^1 x^{n-1} dx$
 $= \alpha_0 + \frac{\alpha_1}{2} + \frac{\alpha_2}{3} + \dots + \frac{\alpha_{n-1}}{n}$

now $m_1 p(t_1) + \dots + m_n p(t_n)$

$= m_1 (\alpha_0 + \alpha_1 t_1 + \dots + \alpha_{n-1} t_1^{n-1})$
 $+ m_2 (\alpha_0 + \alpha_1 t_2 + \dots + \alpha_{n-1} t_2^{n-1})$
 $+ m_3 (\alpha_0 + \alpha_1 t_3 + \dots + \alpha_{n-1} t_3^{n-1})$
 $\vdots$
 $+ m_n (\alpha_0 + \alpha_1 t_n + \dots + \alpha_{n-1} t_n^{n-1})$

$= \alpha_0 (m_1 + m_2 + \dots + m_n)$

$+ \alpha_1 (m_1 t_1 + m_2 t_2 + \dots + m_n t_n)$

$+ \alpha_2 (m_1 t_1^2 + m_2 t_2^2 + \dots + m_n t_n^2)$

$\vdots$
 $+ \alpha_{n-1} (m_1 t_1^{n-1} + m_2 t_2^{n-1} + \dots + m_n t_n^{n-1})$

for distinct $t_i \in [0,1]$

Note: there are n equations, and n variables m_i .

$\therefore \begin{bmatrix} 1 & t_1 & t_1^2 & \dots & t_1^{n-1} \\ 1 & t_2 & t_2^2 & \dots & t_2^{n-1} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & t_n & t_n^2 & \dots & t_n^{n-1} \end{bmatrix}$ if invertible then this exist

for $t_i \in (0,1)$

$1 \neq t_1 \neq t_1^2 \dots$

and $t_i \neq t_j$ for $i \neq j$

$\Rightarrow$ every column is different

$\therefore$ the matrix is invertible.

we know $\dim(X) = n$

it follows that

$\dim(X') = n$

dual $\leftarrow$

space $X \downarrow p \rightarrow \int_0^1 p(x) dx$

$\psi(p) = \int_0^1 p(x) dx$

$\psi: X \rightarrow \mathbb{C}$

linear

$\Rightarrow \psi \in X'$

Since $\psi = \sum_{j=1}^n \alpha_j \delta_{t_j}$

$\forall p \in X, \forall j=1, \dots, n$

$t_j \in [0,1]$

$\delta_{t_j}: X \rightarrow \mathbb{C}$

$p \rightarrow p(t_j)$

$\left\{ \delta_{t_j} \right\}_{j=1}^n$

prove this is ind. in dual space

$\left\{ \delta_{t_j} \right\}_{j=1}^n$

$\Rightarrow \exists m_j, j=1, \dots, n$
 $s.t. \psi = \sum_{j=1}^n m_j \delta_{t_j}$

$\Rightarrow \psi(p) = \sum_{j=1}^n m_j p(t_j)$

$\forall p \in X = \int_0^1 p(x) dx$

tutorial-4:

1. $X \leftarrow$ finite dim. vector space
 $M \in \alpha(X, X)$ $N \in \alpha(X, X)$
 linear map

similar if

$\exists$ invertible $S \in \alpha(X, X)$ s.t.

$$M = SNS^{-1}$$

(i) $M \sim N$ as $M = SNS^{-1}$ $M \sim N$ is M and N is similar

① $M \sim M$ as for $S = I \in \alpha(X, X)$

$$M = IMI^{-1}$$

(Reference)

② $M \sim N$ then

$$\text{for } S' = S^{-1}$$

$$N = S^{-1}MS$$

$$= S'MS'^{-1}$$

(Symmetric)

$$\therefore N \sim M$$

③ if $M \sim N$ and $N \sim P$

then

$$M = S_1 N S_1^{-1}$$

$$N = S_2 P S_2^{-1}$$

$$\text{then } M = S_1 (S_2 P S_2^{-1}) S_1^{-1}$$

$$= (S_1 S_2) P (S_1 S_2)^{-1}$$

$$S = S_1 S_2$$

as S_1, S_2 invertible

S is also invertible

$$\therefore M \sim P$$

(transitive)

(ii) wlog N is invertible. i.e.

$$\exists B \text{ s.t.}$$

$$NB = BN = I$$

$$\text{and } B = N^{-1}$$

now,

$$M = SNS^{-1}$$

$$MN = SNS^{-1}N$$

$$\text{and } NM = NSNS^{-1}$$

now

$$MN = N^{-1}NSNS^{-1}N = N^{-1}(NSNS^{-1})N$$

$$MN = N^{-1}(NM)N$$

$\therefore MN$ and NM are

similar for

$$S' = N$$

(iii) $A = PBP^{-1}$

then

$$Ax = 0 \Leftrightarrow PBP^{-1}x = 0$$

$$\Leftrightarrow BP^{-1}x = 0$$

$$\Leftrightarrow B(P^{-1}x) = 0$$

$$\text{here } Np^{-1} = \{0\}$$

so the $\forall x$ s.t. $Ax = 0$

$$\text{and } B(P^{-1}x) = 0$$

will have two same basis

as if Basis = $\{x_1, \dots, x_n\}$

Basis for $P^{-1}x = \{P^{-1}(x_1), \dots, P^{-1}(x_n)\}$

$$\therefore \dim N_A = \dim N_B$$

$$\Rightarrow \dim R_A = \dim R_B$$

$$I(X, X) \rightarrow I(X, X)$$

$$A \rightarrow SA$$

$$y \in N_A \Rightarrow Ay = 0$$

$$\Rightarrow SAy = 0$$

$$\Rightarrow y \in N_{SA} \Rightarrow N_A \subseteq N_{SA}$$

similarly if $y \in N_{SA}$

$$\Rightarrow SAy = 0$$

$$\Rightarrow Ay = 0$$

$$\Rightarrow y \in N_A$$

$$\therefore N_A = N_{SA}$$

$$\text{now } A \rightarrow AS$$

$$N_A \rightarrow N_{AS}$$



3. $X \leftarrow n$ -dim vector space over F .
 (i) l be a non-zero linear function

$$l: X \rightarrow F$$

$$\dim(X) = \dim(R_l) + \dim(N_l)$$

as $l \neq 0$ $\dim(N_l) \neq \dim(X)$
 $\therefore \dim(N_l) < \dim(X)$
 also $\dim(R_l) < \dim(X)$
 $\dim(N_l) > 0$
 $\dim(R_l) > 0$

$$0 < \dim(N_l) < \dim(X)$$

cii) To prove: $f: X \rightarrow F$
 $f = \alpha l \Leftrightarrow N_l \subseteq N_f$

proof: $(\Rightarrow)$ given $f = \alpha l$
 then if $x \in N_l$
 then $l(x) = 0$
 $\Rightarrow \alpha l(x) = 0$
 $\Rightarrow f(x) = 0$
 $\therefore x \in N_f$
 $\therefore N_l \subseteq N_f$

$(\Leftarrow)$ $f: X \rightarrow F$
 $l: X \rightarrow F$
 and α be some number in F

if f is zero,
 then $\alpha = 0$
 (trivial case)
 if $f \neq 0$ (non-zero
 function) then
 Note that
 $[x] \in N_l$
 $\tilde{f}: \frac{X}{N_l} \rightarrow F$

and α be some number in F
 then
 if $N_l \subseteq N_f$
 then
 $f(N_l) = 0$
 also as f is a linear map

$$f(\alpha'x + y) = \alpha'f(x) + f(y)$$

$$l(\alpha'x + y) = \alpha'l(x) + l(y)$$

Over defined

$x-y \in N_l$ now as $f(x) = g(x) \cdot l(x)$
 $\Rightarrow x-y \in N_f$
 $\Rightarrow f(x) = f(y)$
 $\tilde{f}: \frac{X}{N_l} \rightarrow F$
 $N_l \hookrightarrow [x]$
 $\tilde{f}([x]) = f(x)$
 $\neq 0$

as f is a linear map

$$f(\alpha x + y) = g(\alpha x + y) l(\alpha x + y)$$

$$= (\alpha g(x) + g(y)) (\alpha l(x) + l(y))$$

$$\alpha g(x) + g(y) \in F$$

if not then f is not a linear map

$$\tilde{f}([x]) = l(x) \neq 0$$

$$\frac{f(x)}{l(x)} = \alpha$$

$$f = \alpha l$$

$$\Leftrightarrow f(y) = \alpha l(y)$$

$$\exists \alpha' \in F$$

$$f(y) = \alpha' l(y)$$

$$= \frac{f(x)}{l(x)} l(y)$$

here

$$f(y) = \tilde{f}([y]) \quad y \notin N_l$$

$$= \tilde{f}(\lambda [x])$$

$$= \lambda f(x)$$

(iii) V be a subspace of X $\dim(V) = n-1$

$$\dim X = n$$

$$g: X \rightarrow F$$

$$s.t. N_g = V$$

(ii) (E)

assume $N_l \subseteq N_f$

since $\dim(N_l) = n-1$

as non-zero let

if $f = 0$

$$N_f: X \rightarrow F$$

$$\leftarrow N_f = X$$

also basis of X

can be made as $\{v_1, \dots, v_{n-1}, x_n\}$

$$\frac{f(x)}{l(x)} l(y) = f(x) \tilde{f}([y])$$

$$= \frac{f(x)}{l(x)} \lambda l(x)$$

$$= \lambda f(x) = f(y)$$

See here as l is a linear map
non-zero $l: X \rightarrow F$

$$\exists x \in X \text{ s.t. } (x \neq 0)$$

$$l(x) \neq 0$$

Also $l(X) = F \Rightarrow \forall$
 $\forall x \in X$ is onto over

$$x_0 = l(x)$$

$$l(y) = v$$

$$v = \frac{x_0}{x_0} \cdot v = x_0 \left(\frac{v}{x_0} \right)$$

$$l(y) = x_0 \cdot \frac{v}{x_0} = l(x) \frac{v}{x_0}$$

$$l(y) = l\left(x \frac{v}{x_0}\right)$$

$$\therefore \forall v \in F$$

$$\exists x \frac{v}{x_0} \text{ s.t.}$$

$$l\left(x \frac{v}{x_0}\right) = v$$

$$\therefore \text{onto}$$

This makes
 isomorphism $\tilde{f}: \frac{X}{N_l} \rightarrow F$
 isomorphism $\frac{|X/N_l|}{|F|} = 1$
 $\dim\left(\frac{X}{N_l}\right) = 1$
 $\dim(X) - \dim(N_l) = 1$
 $\dim(N_l) = \dim(X) - 1$
 An isomorphism

See this proof soln

divide by 0 now,
 as $f=0$ for
 $x=0$ $f=0$
 $N_f = x \geq N_e$
 if $\dim N_f$
 $= \dim N_e$
 then $N_f \cong N_e$
 $\tilde{f}: \frac{x}{N_f} \rightarrow \mathbb{C}$

$g(x) = g(\sum \alpha_i v_i + \alpha_n x_n)$
 $= \alpha_n$
 so my function is defined as this.

① well defined as:
 $\sum \alpha_i v_i + \alpha_n x_n = \sum \beta_i v_i + \beta_n x_n$ ($\alpha_n = \beta_n$)
 $\Rightarrow g(\sum \alpha_i v_i + \alpha_n x_n) = g(\sum \beta_i v_i + \beta_n x_n)$

② linear map:

$x + N_f \mapsto f(x)$
 $\tilde{f}: \frac{x}{N_e} \rightarrow \mathbb{C}$
 $x + N_e \mapsto \tilde{f}(x)$
 $\tilde{f}: \frac{x}{N_e} \rightarrow \mathbb{C}$

$$g(\alpha x + y) = g(\alpha \sum \alpha_i v_i + \alpha(\alpha_n x_n) + \sum \alpha'_i v_i + \alpha'_n x_n)$$

$$= \alpha \alpha_n + \alpha'_n$$

$$= \alpha g(x) + g(y)$$

if this is well defined or not
 $N_g = V$

(iv) $g: \mathbb{R}^2 \rightarrow \mathbb{R}$
 N_g is line $ax + by = 0$, $a, b \in \mathbb{R}$

$$g(x, y) = ax + by$$

$$g\left(\begin{pmatrix} x \\ y \end{pmatrix}\right) = ax + by$$

then $\begin{pmatrix} x_1 \\ y_1 \end{pmatrix} = \begin{pmatrix} x_2 \\ y_2 \end{pmatrix} \Rightarrow ax_1 = ax_2$
 $by_1 = by_2$

$$\Rightarrow ax_1 + by_1 = ax_2 + by_2$$

$\therefore$ well defined

Also isomorphism
 as $\text{Basis}(N_e) = \{x_1, \dots, x_{n-1}\}$
 $\text{Basis}(X) = \{x_1, \dots, x_n\}$
 if $\tilde{f}(x_n + N_e) = 0$
 $\Rightarrow f(x_n) = 0$
 $\Rightarrow x_n \in N_f$
 $\tilde{f} = \alpha \tilde{f}$ on $\frac{x}{N_e}$
 $\Rightarrow \tilde{f}(x) = \alpha f(x), \forall x \in X$

now, $g\left(\begin{pmatrix} x \\ y \end{pmatrix} + \alpha \begin{pmatrix} x' \\ y' \end{pmatrix}\right) = g\left(\begin{pmatrix} x + \alpha x' \\ y + \alpha y' \end{pmatrix}\right) = a(x + \alpha x') + b(y + \alpha y')$
 $= ax + by + \alpha ax' + \alpha by'$
 $= g\left(\begin{pmatrix} x \\ y \end{pmatrix}\right) + \alpha g\left(\begin{pmatrix} x' \\ y' \end{pmatrix}\right)$

(iii) let $V \subseteq X$ with $\dim(V) = n-1$
 $\frac{x}{V} \xrightarrow{f_1} \mathbb{C}$
 $f_1(\beta[x_0]) = \beta \alpha \Rightarrow f_1([x_0])$
 general element in the quotient space

4. $T(x_1, x_2) = (-x_2, x_1)$
 (i) $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$
 $\therefore T$ is a 2×2 matrix
 now $T(e_1) = (0, 1)$
 $T(e_2) = (-1, 0)$
 Now $T\left(\begin{pmatrix} 1 \\ 0 \end{pmatrix}\right) = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$
 $T\left(\begin{pmatrix} 0 \\ 1 \end{pmatrix}\right) = \begin{pmatrix} -1 \\ 0 \end{pmatrix}$
 then $T\left(\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}\right) = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$
 $\Rightarrow T(I) = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$
 $\therefore Ax = T(x)$
 s.t $A = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$
 $A\begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} -x_2 \\ x_1 \end{pmatrix}$

$X \xrightarrow{\pi} \frac{X}{V} \xrightarrow{f_1} \mathbb{C}$
 $x \mapsto x + V$
 $f := f_1 \circ \pi$
 $f(x_0) = f_1(\pi(x_0)) = \alpha \neq 0$
 now $N_g = V$
 $\ker(f \circ \pi) = \ker(\pi)$
 $= V$
 $\therefore$ to prove.
 f_1 is injective
 π is surjective
 $f_1(\pi(y)) = 0$
 $\Rightarrow \pi(y) = 0$
 $\Rightarrow y + V = 0 \Rightarrow y \in V$

(ii)

$$T(x) = \sum_{i=1}^n A_{ij} x_i$$

wrt x bases

$$T\left(\begin{pmatrix} 1 \\ 2 \end{pmatrix}\right) = \begin{pmatrix} -2 \\ 1 \end{pmatrix} = A_{11}\begin{pmatrix} 1 \\ 2 \end{pmatrix} + A_{21}\begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

$$T\left(\begin{pmatrix} 1 \\ -1 \end{pmatrix}\right) = \begin{pmatrix} -1 \\ 1 \end{pmatrix} = A_{12}\begin{pmatrix} 1 \\ 2 \end{pmatrix} + A_{22}\begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

$$-2 = A_{11} + A_{21}$$

$$1 = 2A_{11} - A_{21}$$

$$\boxed{-\frac{1}{3} = A_{11}}$$

$$1 = -\frac{2}{3} - A_{21}$$

$$\boxed{A_{21} = -\frac{5}{3}}$$

$$-2 = 2A_{12} + 2A_{22}$$

$$1 = 2A_{12} - A_{22}$$

$$-3 = 3A_{22}$$

$$\boxed{A_{22} = -1}$$

$$\boxed{A_{12} = 0}$$

$$\therefore A = \begin{bmatrix} -1/3 & 0 \\ -5/3 & -1 \end{bmatrix}$$

doubt
(see how to do
this properly)

Tutorial-5:

1. $\det(A) = D(A^*1, A^*2, \dots, A^*n)$

now

$$D(\alpha A^*1, A^*2, \dots, A^*n)$$

$$= \alpha D(A^*1, \dots, A^*n)$$

similary $\alpha^n D(A^*1, \dots, A^*n) = D(\alpha A^*1, \alpha A^*2, \dots, \alpha A^*n)$

$$\alpha^n \det(A) = \det(\alpha A)$$

2. $A^2 = 0$

now $\det(CI - A)$

Note A is 2×2 , so $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$

$$\text{s.t. } A^2 = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} a & b \\ c & d \end{bmatrix} = \begin{bmatrix} a^2+bc & ab+bd \\ ac+cd & d^2+cb \end{bmatrix}$$

$$\text{also } \det(\alpha I - A) = \det \begin{pmatrix} \alpha - a & -b \\ -c & \alpha - d \end{pmatrix}$$

$\det(A) = \sum_{\sigma \in S_2} \text{sgn}(\sigma) a_{\sigma(1)1} a_{\sigma(2)2}$ for 2×2 matrix

$$= a_{11}a_{22} - a_{12}a_{21}$$

$$CI - A = (C - a_{11}) (C - a_{22}) - a_{12}a_{21}$$

$$= C^2 - Ca_{22} - Ca_{11} + a_{11}a_{22} - a_{12}a_{21}$$

$$= C^2 - Ca_{22} - Ca_{11} \quad \text{as } a_{11} = -a_{21}$$

$$= C^2$$

$$= (\alpha - a)(\alpha - d) - (-c)(-b)$$

$$= \alpha^2 - \alpha d - \alpha a + ad - cb$$

$$= \alpha^2 - \alpha(a+d) + ad - cb$$

$$a^2 = d^2 = -bc$$

$$a+d=0$$

$$\text{or } c=0, b=0$$

as if $a+d=0$
then

$$\alpha^2 - \alpha(0) + (a)(-a) + a^2 = \alpha^2$$

if $c=0, b=0$

then evaluating zero
 $\therefore \alpha^2$ only

$$\therefore \det(\alpha I - A) = \alpha^2$$

$$\text{or } \det(CI - A) = C^2$$

3. As $\det(A^T) = \det(A)$

here $\det(A^T) = \det(-A) = (-1)^n \det(A) = \det(A)$

$$\Rightarrow \det(A) = 0$$

as n is odd

4. $AA^T = I$

orthogonal

$$\det(AA^T) = 1$$

$$\Rightarrow \det(A) \det(A^T) = 1$$

$$\Rightarrow \det^2(A) = 1$$

$$\Rightarrow \det(A) = \pm 1$$

if $\det(A) = -1$ then let $A = \begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix}$ also $AA^T = \begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = I$

$$A^T = \begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix}$$

5. S_n permutation group of n -symbols

$$\text{sgn}: S_n \rightarrow \{\pm 1\}$$
$$\sigma \mapsto \text{sgn}(\sigma)$$

now let $N(\sigma_1)$ be number of 2-cycles in σ_1
and $N(\sigma_2)$ be number of 2-cycles in σ_2
Note not unique and for

$$N(\sigma_1 \sigma_2) \equiv N(\sigma_1) + N(\sigma_2) \pmod{2}$$

$$\& \quad (-1)^{N(\sigma_1 \sigma_2)} = (-1)^{N(\sigma_1) + N(\sigma_2)}$$

$$\therefore \text{sgn}(\sigma_1 \circ \sigma_2) = \text{sgn}(\sigma_1) \text{sgn}(\sigma_2)$$

$$\forall \sigma_1, \sigma_2 \in S_n$$

Tutorial 6:

1. $T: \mathbb{F}^n \rightarrow \mathbb{F}^n$ (linear map)

$$\det(T(\alpha_1), \dots, T(\alpha_n)) = c \det(\alpha_1, \dots, \alpha_n)$$

$$c = \det(T(e_1), T(e_2), \dots, T(e_n))$$

as

$$\det(T(\alpha_1), \dots, T(\alpha_n))$$

$$= \det \begin{bmatrix} T\alpha_1 & T\alpha_2 & \dots & T\alpha_n \\ | & | & & | \end{bmatrix}$$

$$= \det \begin{bmatrix} T \\ \hline \end{bmatrix} \begin{bmatrix} \alpha_1 & \alpha_2 & \dots & \alpha_n \end{bmatrix}$$

$$= \det[T] \det[\alpha_1 \ \alpha_2 \ \dots \ \alpha_n] \left(\begin{smallmatrix} \text{det}(AB) \\ = \text{det}(A) \text{det}(B) \end{smallmatrix} \right)$$

$$= \det(T(e_1), T(e_2), \dots, T(e_n)) \det(\alpha_1, \alpha_2, \dots, \alpha_n)$$

2. $A, B \in M_{n \times n}(\mathbb{C})$, $\lambda, \beta \in \mathbb{C}$ s.t

(i) λ is eigenvalue of A , β is eigenvalue of B

$$\text{or } Ax = \lambda x \quad (\text{for some } x \in \mathbb{C}^n)$$

$$By = \beta y \quad (\text{for some } y \in \mathbb{C}^n)$$

$$A = \begin{bmatrix} 0 & 1 \\ -2 & -3 \end{bmatrix}$$

$$A - \lambda I = \begin{bmatrix} -\lambda & 1 \\ -2 & -3 - \lambda \end{bmatrix}$$

$$3\lambda + \lambda^2 - (-2) = 0$$

$$\lambda^2 + 3\lambda + 2 = 0$$

$$\lambda^2 + \lambda + 2\lambda + 2 = 0$$

$$\lambda(\lambda + 1) + 2(\lambda + 1) = 0$$

$$\Rightarrow \lambda = -2, -1$$

$$\text{now, } A = \begin{bmatrix} 0 & 1 \\ -2 & -3 \end{bmatrix}$$

$$B = \begin{bmatrix} 1 & 4 \\ 3 & 2 \end{bmatrix} \quad \beta = 5, -2$$

$$\text{then } A + B = \begin{bmatrix} 1 & 5 \\ 1 & -1 \end{bmatrix}$$

$$(A + B) - \lambda' I = \begin{bmatrix} 1 - \lambda' & 5 \\ 1 & -1 - \lambda' \end{bmatrix}$$

$$(1 - \lambda')(-1 - \lambda') - 5 = 0$$

$$-(1 + \lambda')(1 - \lambda') = 5$$

$$-(1 - \lambda'^2) = 5$$

$$\lambda'^2 - 1 = 5$$

$$\lambda'^2 = 6$$

$$\lambda' = \pm \sqrt{6} \neq \lambda + \beta$$

$$(ii) AB = \begin{bmatrix} 0 & 1 \\ -2 & -3 \end{bmatrix} \begin{bmatrix} 1 & 4 \\ 3 & 2 \end{bmatrix} = \begin{bmatrix} 3 & 2 \\ -11 & -14 \end{bmatrix}$$

$$(3-\lambda)(-14-\lambda) - (-11)(2) = 0$$

$$-42 - 3\lambda + 14\lambda + \lambda^2 + 22 = 0$$

$$\lambda^2 + 11\lambda - 20 = 0$$

$$\lambda = \frac{-11 \pm \sqrt{121 + 80}}{2}$$

$$= \frac{-11 \pm \sqrt{201}}{2}$$

Not
perfect
square

3. $\lambda \leftarrow$ eigenvalue of $A \in M_{n \times n}(\mathbb{F})$

$\lambda^n \leftarrow$ eigenvalue of A^n
for some $x \neq 0$

$$\begin{aligned} Ax &= \lambda x \\ \Rightarrow A^2 x &= A(Ax) = A(\lambda x) \\ &= \lambda(Ax) \\ &= \lambda \cdot \lambda x \\ &= \lambda^2 x \end{aligned}$$

for $n=2$ true

Say $n=k$ true

$$\begin{aligned} \text{then, } A^k x &= \lambda^k x \\ \text{for } A^{k+1} x &= A(A^k x) \\ &= A(\lambda^k x) \\ &= \lambda^k (Ax) \\ &= \lambda^{k+1} x \end{aligned}$$

$\therefore$ By induction

$$\lambda^n x = A^n x$$

or λ^n is eigenvalue of A^n

$P \rightarrow$ polynomial

$$P(A) = \sum_{i=0}^n \alpha_i A^i$$

for $A^0 = I$

$$\begin{aligned} P(A)x &= \sum \alpha_i A^i x \\ &= \sum \alpha_i \lambda^i x \end{aligned}$$

$$P(A)x = P(\lambda)x$$

or $P(\lambda)$ is an eigenvalue of $P(A)$

4. $A \in M_{n \times n}(\mathbb{C})$, nilpotent matrix

$$A^r = 0 \quad A^r = 0 \quad \forall r \in \mathbb{N}$$

say λ is an eigenvalue of A
then

$$Ax = \lambda x$$

$$\lambda \neq 0, \quad x \neq 0$$

$$\Rightarrow A^r x = \lambda^r x$$

$$\Rightarrow 0 = \lambda^r x$$

for this $\lambda \neq 0, x \neq 0$

not possible
so no eigenvalues.

5. $M \sim N$
 $SMS^{-1} = N$

$$\det(N - xI) = \det(SNS^{-1} - xI)$$

$$= \det(M - xI)$$

$$\chi_N(x) = \chi_M(x)$$

$\therefore$ same eigenvalues

Tutorial 7:

1. similar matrices

$$M \sim N$$

$$\exists S \in M_{n \times n}(\mathbb{C}) \text{ s.t. } S M S^{-1} = N$$

$$\chi_N(s) = \det(N - sI)$$

$$\begin{aligned}\chi_N(t) &= \det(S S^{-1}) \det(N - tI) \\ &= \det(S N S^{-1} - t S S^{-1} I) \\ &= \det(M - tI)\end{aligned}$$

$$\therefore \chi_N(t) = \chi_M(t)$$

$\therefore$ same eigenvalues.

2. as $\det T = \det T^t$

$$\det(T + I t)^t = \det(T^t + I t)$$

or

$$\chi_{T^t} = \chi_T$$

3. $T \in M_{n \times n}(\mathbb{C})$

n distinct eigenvalues $\{\lambda_1, \dots, \lambda_n\}$

first guess:

then as $T \sim \begin{bmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_n \end{bmatrix}$, $\exists S \in M_{n \times n}(\mathbb{C})$
s.t.

$$S T S^{-1} = \begin{bmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_n \end{bmatrix}$$

$$\Rightarrow T S = \begin{bmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_n \end{bmatrix} S$$

$$\Rightarrow T S_{*i} = \lambda_i S_{*i}$$

as S is invertible

or: $\{S_{*1}, \dots, S_{*n}\}$ form a basis of $\mathbb{C}^n$

$$\underline{\text{or:}} \quad h = \sum_{i=1}^n \alpha_i S_{*i}$$

this means that $T^m h = T^m \left(\sum \alpha_i S_{*i} \right)$

$$\begin{aligned}&= \sum \alpha_i T^m S_{*i} \\ &= \sum \alpha_i \lambda_i^m S_{*i}\end{aligned}$$

c.i) if $|\lambda_i| < 1 \ \forall i \in \{1, 2, \dots, n\}$

$$\text{as } m \rightarrow \infty \quad |\lambda_i|^m \rightarrow 0$$

$$\text{or } \sum \alpha_i \lambda_i^m S_{*i} \rightarrow 0$$

$$\therefore T^m h \rightarrow 0$$

$$\text{as } m \rightarrow \infty \quad \forall h \in \mathbb{C}^n$$

c.ii) for $\forall r > 0$, $\exists N_0 = \max \left\{ \left\lfloor \log_{|\lambda_i|} \left| \frac{r}{n |\alpha_i| |S_{*i}|} \right| \right\rfloor + 1 \right\}$

s.t a row j :

$$|\sum \alpha_i \lambda_i^m s_{ji}| = \sum |\alpha_i| |\lambda_i|^m |s_{ji}|$$

$$> \sum |\alpha_i| \left(\frac{r}{(n)(\max |s_{ji}|)} \right) |s_{ji}|$$

$$= \sum \frac{r}{n} = r$$

$$|\sum \alpha_i \lambda_i^m s_{ji}| > r$$

or else row $\rightarrow \infty$
 $\therefore T^m$ as $m \rightarrow \infty$
 and $n \neq 0 \in \mathbb{C}^n$
 $\rightarrow \infty$

4. $Tf = \lambda f$ for T to have eigenvalues ($\neq 0$)

$$\int_0^x f(t) dt = \lambda f(x)$$

Note: $f(0) = 0$ — ①

$$\Rightarrow f(x) = \lambda f'(x)$$

now, $\int \frac{1}{\lambda} = \int \frac{f'(x)}{f(x)}$

$$\frac{1}{\lambda} x + c = \ln |f(x)|$$

$$\Rightarrow f(x) = c e^{x/\lambda}$$

Now $f(0) = 0$
 $\Rightarrow c e^{0/\lambda} = 0$
 $\forall x \in \mathbb{R}$
 as $\lambda \neq 0 \Rightarrow c = 0$

but for $c=0$
 $f \equiv 0$ (eigenvector should be non zero)
 $\therefore$ No eigenvalue of T .

5. $A, B \in M_{n \times n}(\mathbb{F})$

$$C = (I - AB)^{-1}$$

$$C(I - AB) = I$$

$$C - CAB = I$$

$$C = I + CAB \text{ — ①}$$

now, $[I + BCA][I - BA]$
 $= I - BA + BCA - BCABA$
 $= I - BA + BCA(I - BA)$
 $= (I - BA)(I + BCA) \text{ — ②}$

also $I - BA + BCA - BCABA = I - \cancel{BA} + \cancel{BCA} - \cancel{BCA}A$
 $= I$ from ①

Tutorial sheet 8:

1. $A \in M_{2 \times 2}(\mathbb{C})$ rank 1 matrix

$$\text{or } A = \begin{bmatrix} a & ta \\ b & tb \end{bmatrix}$$

$$\begin{aligned} \text{now, } \det(A - \lambda I) &= (a - \lambda)(tb - \lambda) - tab \\ &= atb - a\lambda - tb\lambda + \lambda^2 - \cancel{tab} \\ &= 0 \end{aligned}$$

$$\begin{aligned} \lambda^2 &= a\lambda + tb\lambda \\ \Rightarrow \lambda &= 0 \quad \text{or} \quad \lambda = a + tb \end{aligned}$$

as λ has 2 distinct values $\Rightarrow A \sim$ diagonal matrix
 $\Rightarrow A$ is diagonalisable

2. $T = \begin{bmatrix} 0 & 0 & 0 & 0 \\ a & 0 & 0 & 0 \\ 0 & b & 0 & 0 \\ 0 & 0 & c & 0 \end{bmatrix} \rightarrow$ Real matrix

$$\chi_T(t) = \det \begin{bmatrix} t & 0 & 0 & 0 \\ -a & t & 0 & 0 \\ 0 & -b & t & 0 \\ 0 & 0 & -c & t \end{bmatrix}$$

$$\begin{aligned} &= t^4 \\ \text{now } t^4 &= 0 \\ \Rightarrow \lambda &= 0 \text{ is only eigenvalue of } T \end{aligned}$$

or by the theorem

$$P(t) = (t - 0)^4 \text{, poly of } T$$

$$\begin{aligned} \Rightarrow P(T) &= T = 0 \\ \Rightarrow a &= b = c = 0 \end{aligned}$$

3. A is 2×2 symmetric i.e. $A^T = A$

To prove: A is diagonalisable

Proof: As $A^T = A$

$$\begin{bmatrix} a & b \\ b & d \end{bmatrix} = A \quad \text{as } A = A^T$$

now

$$\begin{aligned} \chi_A(t) &= \det \begin{bmatrix} a-t & b \\ b & d-t \end{bmatrix} = ad - at - bt + t^2 - b^2 \\ &= 0 \end{aligned}$$

$$t^2 - (a+d)t + ad - b^2 = 0$$

$$\lambda = \frac{(a+d) \pm \sqrt{a^2 + d^2 + 2ad - 4ad + 4b^2}}{2}$$

$$\lambda = \frac{a+d \pm \sqrt{(a-d)^2 + 4b^2}}{2}$$

$\therefore$ diff $\lambda \Rightarrow A \sim$ diagonal matrix

4. $A \in M_{n \times n}(\mathbb{C})$ s.t.
 $A^K = 0$ for some $K \in \mathbb{N}$

or as $A^K = 0$ we have a polynomial

$$f(x) = x^K$$

s.t. $f(A) = A^K = 0$

or $f(x) \in \langle p \rangle$

$\hookrightarrow$ minimal poly of A

then $p(x) \mid f(x)$

$$p(x) \mid x^K \Rightarrow p(x) = x^m \text{ where } m \leq K$$

as roots of minimal poly = eigenvalues
 we have

$$p(x) = x^m = 0$$

$$\Rightarrow \underline{x = 0}$$

or $x = 0$ is the eigenvalue of A

$$Ax = 0$$

for some $x \neq 0$

$$\Rightarrow \chi_A(x) = x^n$$

as $\deg \chi_A = n$

& also

roots of $\chi_A(x)$
 = roots of $p(x)$

$\Rightarrow$ By Cayley Hamilton theorem

$$\chi_A(A) = 0$$

$$\Rightarrow A^n = 0$$

5. $N \in M_{2 \times 2}(\mathbb{C})$ s.t. $N^2 = 0$ or $N \sim \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}$

assume that $N \neq 0$ then

$$\exists x \neq 0 \text{ in } \mathbb{C}^2 \text{ s.t. } Nx \neq 0$$

$\{x, Nx\}$ basis for $\mathbb{C}^2$

or N is cyclic nilpotent $\therefore N \sim \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}$

$$a) \quad T^2 x = 0 \cdot x + (1)(Tx) \\ T^2 x = 0 \cdot x + (0)Tx$$

$$\text{or } T \sim \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}$$

6. $T: M_{n \times n}(F) \longrightarrow M_{n \times n}(F)$ defined by

$$B \longmapsto AB \\ \uparrow \\ \text{fixed}$$

if $\lambda \in \sigma(T)$ then $\exists C \in M_{n \times n}(F) \neq 0$

$$\text{s.t. } T(C) = AC = \lambda C$$

$$\text{or } AC = \lambda C$$

$$(A - \lambda I)C = 0$$

$$\text{as } C \neq 0 \Rightarrow A - \lambda I = 0 \\ \Rightarrow \lambda \in \sigma(A)$$

$$\therefore \forall \lambda \in \sigma(T) \Rightarrow \lambda \in \sigma(A)$$

now if $\lambda \in \sigma(A)$ then

$$A - \lambda I = 0 \\ \Rightarrow (A - \lambda I)C = 0 \text{ for non-zero } C$$

$$\Rightarrow T(C) - \lambda(C) = 0$$

$$\Rightarrow TC = \lambda C$$

$$\Rightarrow \lambda \in \sigma(T)$$

$$\text{so } \sigma(T) = \sigma(A)$$

as eigenvalues same $\Rightarrow$ roots of minimal polynomial of T
 $=$ roots of minimal polynomial of A

as roots same & minimal poly same

$$\Rightarrow P_T = P_A$$

Tutorial-9:

1. (a) $\begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & -2 \\ 0 & 1 & 3 \end{bmatrix} \chi_A(t) = -(t-2)(t-1)^2$
now

$$\text{Nullity}(A - I) = 2$$

or

$$\text{KM}(A - I) = 2$$

$$\therefore \begin{bmatrix} (1) \\ (1) \\ (2) \end{bmatrix}$$

(b) $\begin{bmatrix} 1 & 2 & 0 & 0 \\ 0 & 1 & 2 & 0 \\ 0 & 0 & 1 & 2 \\ 0 & 0 & 0 & 1 \end{bmatrix} \chi_A(t) = (t-1)^4$

now $\text{nullity} \begin{bmatrix} 0 & 2 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 2 \\ 0 & 0 & 0 & 0 \end{bmatrix} = 1 = \text{KM}(A)$
 $A - I$

$$\therefore J = \begin{bmatrix} 1 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

(c) $\begin{bmatrix} 0 & 1 & 1 \\ 2 & 1 & -1 \\ -6 & -5 & 3 \end{bmatrix} \chi_A(\lambda) = -(\lambda-2)(\lambda^2-2\lambda-2)$
 $= -(\lambda-2)\left(\lambda - \left(\frac{2+\sqrt{4+8}}{2}\right)\right)\left(\lambda - \left(\frac{2-\sqrt{12}}{2}\right)\right)$
 $= -(\lambda-2)(\lambda-1-\sqrt{3})(\lambda-1+\sqrt{3})$

$$P_A(\lambda) = (\lambda-2)(\lambda-1-\sqrt{3})(\lambda-1+\sqrt{3})$$

$$J = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 1+\sqrt{3} & 0 \\ 0 & 0 & 1-\sqrt{3} \end{bmatrix}$$

2. $\chi_A(\lambda) = (\lambda)^n$
 $P_A(\lambda) = (\lambda)^n$
 $\text{KM}(A) = 1$

$$J = \begin{bmatrix} 0 & 1 & & \\ & \ddots & \ddots & \\ & & 0 & 1 \\ & & & 0 \end{bmatrix}_{n \times n}$$

x_1 s.t. $Ax_1 = 0$
 x_2 s.t.
 $x_1 = Ax_2$

$$\begin{array}{lcl}
 x \neq 0 & & \\
 \text{then} & \begin{array}{c} T^{n-1}x \\ T^{n-2}x \\ \vdots \\ x \end{array} & \begin{array}{l} \text{as } x_1 = T^{n-1}x \\ x_2 = T^{n-2}x \\ \vdots \\ x_n = x \end{array}
 \end{array}
 \quad \forall x \neq 0$$

3. $J_r(\lambda)$ = Jordan block of λ with $r \times r$

$$J_r(\lambda) = \begin{bmatrix} \lambda & & & \\ & \lambda & & \\ & & \ddots & \\ & & & \lambda \end{bmatrix}_{r \times r}$$

$$T \sim \begin{bmatrix} J_{n_1}(\alpha) & 0 & & 0 \\ 0 & J_{n_2}(\alpha) & & 0 \\ 0 & 0 & J_{m_1}(\beta) & 0 \\ 0 & 0 & 0 & J_{m_2}(\beta) \end{bmatrix}$$

then minimal polynomial of

$$P_T(\lambda) = (\lambda - \alpha)^{s_1} (\lambda - \beta)^{s_2}$$

$$s_1 = \max \{n_1, n_2\}$$

$$s_2 = \max \{m_1, m_2\}$$

4. minimal poly

$$P_A(x) = (x-1)^3 (x-2)^2$$

of 5×5

$$\& \chi_A(x) = (x-1)^3 (x-2)^2$$

$$\& J = \begin{bmatrix} \begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix} & 0 \\ 0 & \begin{pmatrix} 2 & 1 \\ 0 & 2 \end{pmatrix} \end{bmatrix}_{5 \times 5}$$

$$5. (x-1)^3 (x-2)^2 = \chi_A(x)$$

then Jordan form:

$$P_A(x) = (x-1)(x-2)$$

$$\begin{bmatrix} (1) & (1) & (1) & (2) & (2) \end{bmatrix}$$

$$P_A(x) = (x-1)^2 (x-2)$$

$$\begin{bmatrix} (1) & (1) & (1) & (2) & (2) \end{bmatrix}$$

$$(x-1)(x-2)^2$$

$$\begin{bmatrix} (1) & (1) & (1) & (2) & (2) \end{bmatrix}$$

$$(x-1)^2 (x-2)$$

$$\begin{bmatrix} (1) & (1) & (1) & (2) & (2) \end{bmatrix}$$

$$p_A(x) = (x-1)^3 (x-2)$$

$$\left[\begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix} \right]_{(2)(2)}$$

$$(x-1)^3 (x-2)^2$$

$$\left[\begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix} \right]_{\begin{pmatrix} 2 & 1 \\ 0 & 2 \end{pmatrix}}$$

Tutorial-10:

1. V is f.d IPS
for $x, y \in V$

To prove: $\langle x|y \rangle = \frac{1}{4} \sum_{k=0}^3 i^k \|x + i^k y\|^2$

proof: have

$$\langle x|y \rangle = \operatorname{Re} \langle x|y \rangle + i \operatorname{Im} \langle x|y \rangle$$

now, $\|x + y\|^2 = \langle x + y | x + y \rangle$
 $\|x - y\|^2 = \langle x - y | x - y \rangle$

$$\Rightarrow \frac{\|x + y\|^2 - \|x - y\|^2}{4} = \operatorname{Re} \langle x|y \rangle$$

$$\Rightarrow \frac{1}{4} [\|x + y\|^2 + i^2 \|x + i^2 y\|^2] = \operatorname{Re} \langle x|y \rangle$$

$$\begin{aligned} \langle x|y \rangle &= \operatorname{Re} \langle x|y \rangle + i \operatorname{Im} \langle x|y \rangle \\ i \langle x|y \rangle &= i \operatorname{Re} \langle x|y \rangle - \operatorname{Im} \langle x|y \rangle \\ \langle x|iy \rangle &= -i \operatorname{Re} \langle x|y \rangle + i \operatorname{Im} \langle x|y \rangle \\ &= \operatorname{Re} \langle x|iy \rangle + i \operatorname{Im} \langle x|iy \rangle \end{aligned}$$

$$\Rightarrow \operatorname{Re} \langle x|iy \rangle = \operatorname{Im} \langle x|y \rangle$$

$$\Rightarrow i \operatorname{Re} \langle x|iy \rangle = i \operatorname{Im} \langle x|y \rangle$$

now $\langle x|y \rangle = \operatorname{Re} \langle x|y \rangle + i \operatorname{Im} \langle x|y \rangle$
 $\langle x|y \rangle = \operatorname{Re} \langle x|y \rangle + i [\operatorname{Re} \langle x|iy \rangle]$

$$\langle x|y \rangle = \frac{1}{4} \sum_{k=0}^3 i^k \|x + i^k y\|^2$$

2. V is IPS with ONB $\{x_1, \dots, x_n\} = B$
 $\alpha_1, \alpha_2, \dots, \alpha_n \in F$ (scalars)

To find: $x \in V$ s.t. $\langle x, x_i \rangle = \alpha_i \quad \forall i = 1, \dots, n$

let $x = \sum_{i=1}^n c_i x_i$ then

$$\langle x | x_i \rangle = \sum_{j=1}^n c_j \langle x_j | x_i \rangle$$

putting $c_i = \alpha_i$ we get

$$x = \sum \alpha_i x_i \quad \text{s.t.} \quad \langle x | x_i \rangle = \alpha_i$$

this is unique as if $x = \sum c_i x_i$
 $x = \sum \alpha_i x_i$
then $c_i = \alpha_i \quad \forall i$

3. (a) $\langle A | B \rangle = \text{tr}(AB^*)$ is inner product on $M_{n \times n}(\mathbb{C})$:

$$\begin{aligned} \textcircled{1} \langle A+B | C \rangle &= \text{tr}((A+B)C^*) \\ &= \text{tr}(AC^* + BC^*) \\ &= \text{tr}(AC^*) + \text{tr}(BC^*) \\ &= \langle A | C \rangle + \langle B | C \rangle \end{aligned}$$

$$\begin{aligned} \textcircled{2} \langle A | A \rangle &= \text{tr}(AA^*) = \sum_i \left(\sum_j a_{ij} \overline{a_{ji}} \right) \\ &= \sum_i \left(\sum_j a_{ij} \overline{a_{ij}} \right) \end{aligned}$$

$$\text{as } a_{ij} \overline{a_{ij}} \geq 0 \Rightarrow \langle A | A \rangle \geq 0$$

$$\begin{aligned} \textcircled{3} \langle cA | B \rangle &= \text{tr}(cAB^*) \\ &= c \text{tr}(AB^*) \\ &= c \langle A | B \rangle \end{aligned}$$

$$\begin{aligned} \textcircled{4} \overline{\langle A | B \rangle} &= \overline{\text{tr}(AB^*)} = \text{tr}(\overline{AB^*}) = \text{tr}(\overline{AB^*})^T \\ &= \text{tr}((AB^*)^*) \\ &= \text{tr}(BA^*) \\ &= \langle B | A \rangle \end{aligned}$$

$$(b) W = \text{span} \left\{ \begin{bmatrix} 1 & 0 & 0 \\ 0 & \ddots & 0 \\ 0 & \ddots & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 & 0 \\ 0 & \ddots & 0 \\ 0 & \ddots & 0 \end{bmatrix}, \dots, \begin{bmatrix} 0 & 0 & 1 \\ 0 & \ddots & 0 \\ 0 & \ddots & 0 \end{bmatrix} \right\}$$

$$W^\perp = \{ \alpha \in V \mid \langle \alpha | B \rangle = 0 \ \forall B \in W \}$$

↓
orthocomplement of W

$$\langle \alpha | B \rangle = 0 \ \forall B \in W$$

$$\Rightarrow \langle A | B \rangle = \text{tr}(AB^*) = 0 \ \forall B \in W$$

as this is true for every $B \in W$
for $B = \begin{bmatrix} 1 & 0 & 0 \\ 0 & \ddots & 0 \\ 0 & \ddots & 0 \end{bmatrix}$

$$B^* = \begin{bmatrix} 1 & 0 & 0 \\ 0 & \ddots & 0 \\ 0 & \ddots & 0 \end{bmatrix}$$

$$AB^* = \begin{bmatrix} a_{11} & a_{12} & \dots \\ a_{21} & & \\ \vdots & & \\ \vdots & & a_{nn} \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & \ddots & 0 \\ 0 & \ddots & 0 \end{bmatrix}$$

$$\text{similarly } \text{tr}(AB^*) = a_{11} = 0 \quad \text{or} \quad a_{11} = 0$$

$$\text{similarly } a_{ii} = 0 \ \forall i$$

$\therefore W^\perp =$ Subspace of all matrices with diagonal 0.

9. In $\mathbb{C}^3$

To find: orthonormal Basis (ONB) for

$$W = \text{span} \left\{ \begin{pmatrix} 1 \\ 0 \\ i \end{pmatrix}, \begin{pmatrix} 2 \\ 1 \\ 1+i \end{pmatrix} \right\}$$

$$\alpha_1 = \begin{pmatrix} 1 \\ 0 \\ i \end{pmatrix}$$

$$\alpha_2 = \begin{pmatrix} 2 \\ 1 \\ 1+i \end{pmatrix} - \frac{\langle (2, 1, 1+i) | (1, 0, i) \rangle}{\langle (1, 0, i) | (1, 0, i) \rangle} \begin{pmatrix} 1 \\ 0 \\ i \end{pmatrix}$$

$$= \begin{pmatrix} 2 \\ 1 \\ 1+i \end{pmatrix} - \frac{\langle 2 \cdot 1 + 1 \cdot 0 + (1+i)(-i) \rangle}{\langle 1 \cdot 1 + i \cdot (-i) \rangle} \begin{pmatrix} 1 \\ 0 \\ i \end{pmatrix}$$

$$= \begin{pmatrix} 2 \\ 1 \\ 1+i \end{pmatrix} - \frac{(3-i)}{2} \begin{pmatrix} 1 \\ 0 \\ i \end{pmatrix}$$

$$= \begin{pmatrix} 2 - (3-i)/2 \\ 1 - (3-i)/2 \\ 1+i - (3-i)i/2 \end{pmatrix} = \begin{pmatrix} 2 - 3/2 + i/2 \\ 1 - 3/2 + i/2 \\ 1+i - 3i/2 - 1/2 \end{pmatrix}$$

$$= \begin{pmatrix} 1/2 + i/2 \\ 1/2 - i/2 \\ 1/2 - i/2 \end{pmatrix}$$

$$\frac{\alpha_1}{\|\alpha_1\|} = \frac{(1, 0, i)}{\sqrt{1 \cdot 1 + i(-i)}} = \frac{(1, 0, i)}{\sqrt{2}}$$

$$\frac{\alpha_2}{\|\alpha_2\|} = \frac{(1+i, 2, 1-i)}{\sqrt{1+1+4+1+1}} = \frac{(1+i, 2, 1-i)}{\sqrt{8}} = \frac{(1+i, 2, 1-i)}{2\sqrt{2}}$$

$$= \frac{(1/2 + i/2, 1, 1/2 - i/2)}{\sqrt{2}}$$

$$\therefore \text{ONB} = \left\{ \frac{\alpha_1}{\|\alpha_1\|}, \frac{\alpha_2}{\|\alpha_2\|} \right\}$$

(b) Best approximation of $(0, i, 0)$ in W is:

$$\beta = \langle \frac{\alpha_1}{\|\alpha_1\|} | (0, i, 0) \rangle \frac{\alpha_1}{\|\alpha_1\|} + \langle \frac{\alpha_2}{\|\alpha_2\|} | (0, i, 0) \rangle \frac{\alpha_2}{\|\alpha_2\|}$$

$$= \frac{1}{\sqrt{2}} \times \frac{1}{\sqrt{2}} \left\langle \left(\frac{1}{2} + \frac{i}{2}, 1, \frac{1-i}{2} \right) \middle| (0, i, 0) \right\rangle \left(\frac{1}{2} + \frac{i}{2}, 1, \frac{1-i}{2} \right)$$

$$= \frac{1}{2} (-i) \left(\frac{1+i}{2}, 1, \frac{1-i}{2} \right)$$

5. $M_{n \times n}(\mathbb{C})$ IPS

$$\langle A | B \rangle = \text{tr}(AB^*) \quad \forall A, B \in M_{n \times n}(\mathbb{C})$$

$$T_P: M_{n \times n}(\mathbb{C}) \rightarrow M_{n \times n}(\mathbb{C})$$

$$A \mapsto P^{-1}AP$$

P is
invert

now $\langle T_P(A) | B \rangle = \langle A | (T_P)^*(B) \rangle$

$$\begin{aligned} \text{tr}(P^{-1}AP B^*) &= \langle T_P(A) | B \rangle \\ &= \text{tr}(AP B^* P^{-1}) \\ &= \text{tr}(A [(P^*)^{-1} B P^*]^*) \\ &= \langle A | (P^*)^{-1} B P^* \rangle \\ &= \langle A | T_{P^*}(B) \rangle = \langle A | (T_P)^*(B) \rangle \\ &\Rightarrow T_{P^*} = (T_P)^* \end{aligned}$$

6. (i) $A = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}$

then $A^* = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} = A \therefore \text{Normal}$

now $\det(A - \lambda I) = (\lambda - 1)^2 - 1 = (\lambda - 1 - 1)(\lambda - 1 + 1)$
 $= (\lambda - 2)(\lambda)$

or $\exists$ Basis s.t.
 $A \sim \begin{bmatrix} 2 & 0 \\ 0 & 0 \end{bmatrix}$

now, $A = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}$

then $\text{Null} \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} = \left\{ x \mid \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \right\}$
 $x_1 + x_2 = 0$

or
 $\text{Null} \begin{pmatrix} 1 \\ 1 \end{pmatrix} = \text{span} \left\{ \begin{pmatrix} 1 \\ -1 \end{pmatrix} \right\}$

so one of the v row is $\begin{pmatrix} 1 \\ -1 \end{pmatrix} \frac{1}{\sqrt{2}}$

now $\begin{matrix} \swarrow (1,1) \text{ is } \perp \text{ to } (1,-1) \\ \downarrow \end{matrix}$

$\therefore \begin{bmatrix} 1/\sqrt{2} & 1/\sqrt{2} \\ 1/\sqrt{2} & -1/\sqrt{2} \end{bmatrix} = U$ s.t. $\begin{bmatrix} 1/\sqrt{2} & 1/\sqrt{2} \\ 1/\sqrt{2} & -1/\sqrt{2} \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} \cdot \\ \cdot \\ - \end{bmatrix}$
 $= \begin{bmatrix} \sqrt{2} & \sqrt{2} \\ 0 & 0 \end{bmatrix} \begin{bmatrix} \cdot \\ \cdot \\ \cdot \end{bmatrix} = \begin{bmatrix} 2 & 0 \\ 0 & 0 \end{bmatrix}$

$$(ii) B = \begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix} \quad B^* = \begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix}$$

$\therefore B$ is normal

$$\begin{aligned} \text{now, } (x-1)(x-1) - (-2)(-2) &= 0 \\ &= (x-1)^2 - (2)^2 \\ &= (x-1-2)(x-1+2) \\ &= (x-3)(x+1) \end{aligned}$$

$$\chi_B(x) = (x+1)(x-3)$$

$$\text{now } \text{Null} \begin{bmatrix} 2 & 2 \\ 2 & 2 \end{bmatrix} = \text{span} \left\{ \begin{pmatrix} 1 \\ -1 \end{pmatrix} \right\}$$

$$\text{Null} \begin{bmatrix} -2 & 2 \\ 2 & -2 \end{bmatrix} = \text{span} \left\{ \begin{pmatrix} 1 \\ 1 \end{pmatrix} \right\}$$

$$\text{or } U = \begin{bmatrix} 1/\sqrt{2} & 1/\sqrt{2} \\ 1/\sqrt{2} & -1/\sqrt{2} \end{bmatrix}$$

7. Normal or $AA^* = A^*A$
and $A^m = 0$
for some $m \in \mathbb{N}$

then $m=1$ (trivial)

for $m > 1$ we have

$$\begin{aligned} &AA^* = A^*A \\ &\& A^m = 0 \\ \text{now as } &AA^* = A^*A \\ &\exists U \text{ s.t.} \end{aligned}$$

$$\begin{array}{c} U^* A U = I \\ \uparrow \quad \uparrow \\ \text{diagonal} \\ \text{or normal Basis} \\ \text{(unitary operator)} \end{array}$$

$$U^* A U = I$$

now as A is nilpotent

$$(U^* A U)^m = U^* A^m U = 0$$

$$\begin{aligned} &\text{or} \\ &U^* A U \text{ is nilpotent} \\ &\Rightarrow 1^m = 0 \end{aligned}$$

$$\text{diagonal matrix } 1^m = 0 \Rightarrow a_{ii}^m = 0 \Rightarrow a_{ii} = 0$$

$$\therefore 1 \text{ is } 0 \Rightarrow U^* A U = 0 \Rightarrow U^* A = 0 \Rightarrow A = 0 \therefore A \text{ is } 0.$$

